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Algebra 42 - Visualizing Linear Equations in Three Variables Algebra 56 - A Geometrical View of Gauss-Jordan Elimination *Linearity: Definition* Linear Systems Theory Number of Solutions of a Linear System

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Mod-05 Lec-12 Review of Matrix Theory - **IOral History of Peter Hart** Stanford Lecture: Donald Knuth - "Platologic Computation" (October 24, 2006)

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A self-contained, highly motivated and comprehensive account of basic methods for analysis and application of linear systems that arise in signal processing problems in communications, control, system identification and digital filtering.

This volume constitutes the proceedings of the International Symposium on Design and Implementation of Symbolic Computation Systems (DISCO '93), held in Gmunden, Austria, in September 1993. The growing importance of systems for symbolic computation has greatly influenced the decision of organizing this third conference in the series: DISCO '93 focuses mainly on the most innovative methodological and technological aspects of the design and implementation of hardware and software systems for symbolic and algebraic computation,

automated reasoning, geometric modeling and computation, and automatic programming. The general objective of DISCO '93 is to present an up-to-date view of the field and to serve as a forum in symbolic computation for the scientific exchange among academic, industrial and user communities. Besides invited talks by Buchberger, Monagan, Omodeo and Hong, the volume contains 28 contributions, carefully selected by a highly competent international program committee from a total of 56 submissions.

The past few decades have witnessed an increasing interest in the field of multidimensional systems theory. This is concerned with systems whose trajectories depend not on one single variable (usually interpreted as time or frequency), but on several independent variables, such as the coordinates of an image. The behavioural approach introduced by J. C. Willems provides a particularly suitable framework for developing a linear systems theory in several variables. The book deals with the classical concepts of autonomy, controllability, observability, and stabilizability. All the tests and criteria given are constructive in the sense that algorithmic versions may be implemented in modern computer algebra systems, using Gröbner basis techniques. There is a close connection between multidimensional systems theory and robust control of one-dimensional systems with several uncertain parameters. The central link consists in the basic tool of linear fractional transformations. The book concludes with examples from the theory of electrical networks.

Linear System Theory, Second Edition, outlines the basic theory of linear systems in a unified, accessible, and careful manner, with parallel, independent treatment of continuous-time and discrete-time linear systems.

Balancing rigorous theory with practical applications, Linear Systems: Optimal and Robust Control explains the concepts behind linear systems, optimal control, and robust control and illustrates these concepts with concrete examples and problems. Developed as a two-course book, this self-contained text first discusses linear systems, including controllability, observability, and matrix fraction description. Within this framework, the author develops the ideas of state feedback control and observers. He then examines optimal control, stochastic optimal control, and the lack of robustness of linear quadratic Gaussian (LQG) control. The book subsequently presents robust control techniques and derives  $H^\infty$  control theory from the first principle, followed by a discussion of the sliding mode control of a linear system. In addition, it shows how a blend of sliding mode control and  $H^\infty$  methods can enhance the robustness of a linear system. By learning the theories and algorithms as well as exploring the examples in Linear Systems: Optimal and Robust Control, students will be able to better understand and ultimately better manage engineering processes and systems.

Subspace Identification for Linear Systems focuses on the theory, implementation

and applications of subspace identification algorithms for linear time-invariant finite-dimensional dynamical systems. These algorithms allow for a fast, straightforward and accurate determination of linear multivariable models from measured input-output data. The theory of subspace identification algorithms is presented in detail. Several chapters are devoted to deterministic, stochastic and combined deterministic-stochastic subspace identification algorithms. For each case, the geometric properties are stated in a main 'subspace' Theorem. Relations to existing algorithms and literature are explored, as are the interconnections between different subspace algorithms. The subspace identification theory is linked to the theory of frequency weighted model reduction, which leads to new interpretations and insights. The implementation of subspace identification algorithms is discussed in terms of the robust and computationally efficient RQ and singular value decompositions, which are well-established algorithms from numerical linear algebra. The algorithms are implemented in combination with a whole set of classical identification algorithms, processing and validation tools in Xmath's ISID, a commercially available graphical user interface toolbox. The basic subspace algorithms in the book are also implemented in a set of Matlab files accompanying the book. An application of ISID to an industrial glass tube manufacturing process is presented in detail, illustrating the power and user-friendliness of the subspace identification algorithms and of their implementation in ISID. The identified model allows for an optimal control of the process, leading to a significant enhancement of the production quality. The applicability of subspace identification algorithms in industry is further illustrated with the application of the Matlab files to ten practical problems. Since all necessary data and Matlab files are included, the reader can easily step through these applications, and thus get more insight in the algorithms. Subspace Identification for Linear Systems is an important reference for all researchers in system theory, control theory, signal processing, automation, mechatronics, chemical, electrical, mechanical and aeronautical engineering.

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